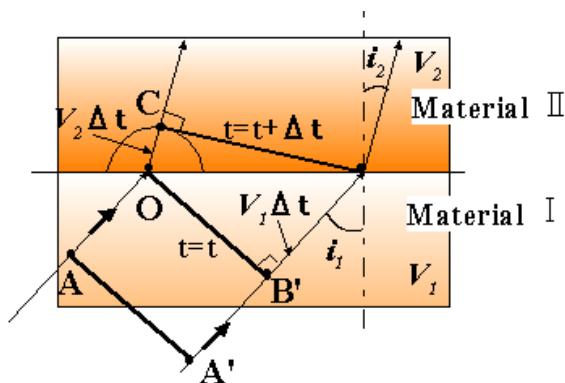
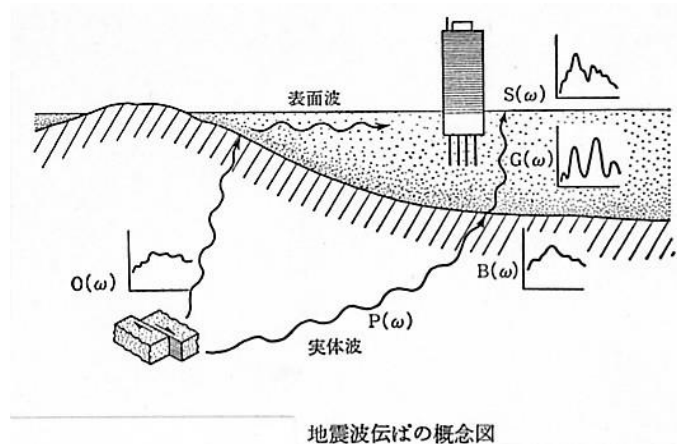
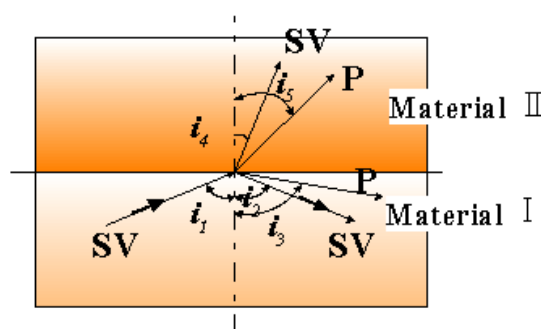


—平面波の屈折と反射 (Refraction and Reflection of Plane Wave)



(a) Reflection



(b) Refraction and Reflection

$$\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = V_s^2 \nabla^2 \mathbf{u} \tag{9.1}$$

$$u = u(v_x x + v_y y + v_z z - Vt) \tag{9.2}$$

$$v_x^2 + v_y^2 + v_z^2 = 1 \tag{9.3}$$

$\mathbf{v} = (v_x, v_y, v_z)$: 方向余弦(*directional cosine*)

plane equation with $\mathbf{v} =$ 進行波の特性曲線(*characteristic curve for progressive wave*)

$$p = v_x x + v_y y + v_z z - Vt = \text{const} : \tag{9.4}$$

波面(*Wave Front*)

$$u = u(p) \tag{9.5}$$

[仮定] 境界面で応力と変位が連続(*Continuity of stresses and displacements on the interface*)

屈折(*Reflection*)

入射角 i_1

$$\sin i_1 = \frac{V_1 \Delta t_1}{OO'} \quad (9.6)$$

入射角 i_2

$$\sin i_2 = \frac{V_2 \Delta t_1}{OO'} \quad (9.7)$$

見かけ速度 V_a (*Apparent Velocity*): 境界面に沿って伝わる波

$$\frac{V_1}{\sin i_1} = \frac{V_2}{\sin i_2} = V_a \quad (9.8)$$

反射(*Refraction*)

$$\sin(\pi - i_2) = \sin(\pi - i_1) \quad (9.9)$$

臨界角 i_c (*Critical Angle*): 全反射となる角度 $i_2 = \frac{\pi}{2}$

$$\sin i_c = \frac{V_1}{V_2} \quad (9.10)$$

見かけ速度 V_a (*Apparent Velocity*): 境界面に沿って伝わる波

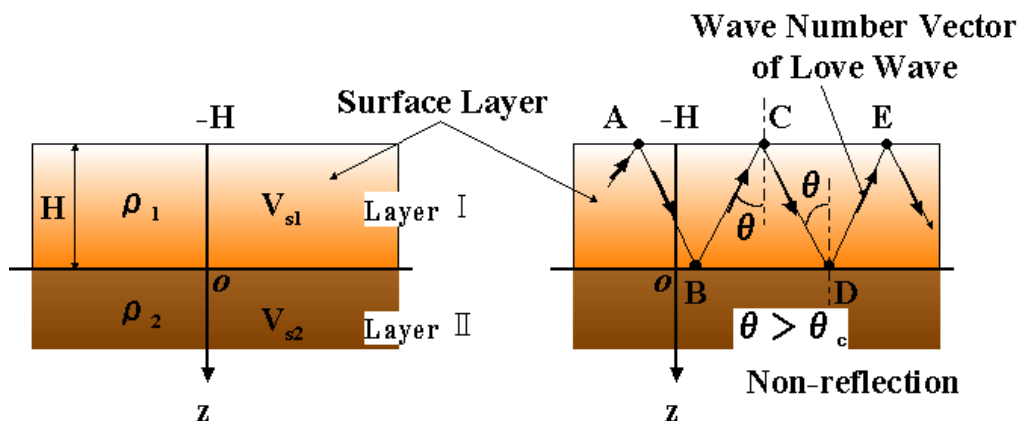
$$V_a = \frac{V_{s1}}{\sin i_1} = \frac{V_{s1}}{\sin i_2} = \frac{V_{p1}}{\sin i_3} = \frac{V_{s2}}{\sin i_4} = \frac{V_{p2}}{\sin i_5} \quad (9.11)$$

— 実体波と表面波

- 実体波 (**Body Wave**) : 圧縮波 (P 波)、せん断波 (S 波 : SH 波、SV 波)
 - ・半球面波 (距離 $r/2$ で減衰)
- 表面波 (**Surface Wave**) : 自由境界の存在 (表面の存在)、
 - ・地震以外の振動源として交通振動 (道路、鉄道)、工事振動
 - ・卓越周期は一般に数秒から数十秒:
 - 一般の構造物では影響小
 - 大規模構造物では考慮
 - 長大橋梁や管路構造物における入力位相問題
 - ・ **Love Wave** (層状地盤 SH 波) : 伝播方向の面外
 - ・ **Rayleigh Wave** (半無限体 P 波+SV 波) : 伝播方向の面内
 - ・ レイリー波は円筒波 (距離 $r^{1/2}$ で減衰)
 - ・ 波長の 1.5 倍の深さで減衰

— 弾性表面波 (**Elastic Surface Waves**)

(a) **Love Wave**



$$\left. \begin{aligned} \frac{\partial^2 u_{y1}}{\partial t^2} &= V_{s1}^2 \frac{\partial^2 u_{y1}}{\partial x^2} & -H \leq z \leq 0 \\ \frac{\partial^2 u_{y2}}{\partial t^2} &= V_{s2}^2 \frac{\partial^2 u_{y2}}{\partial x^2} & z > 0 \end{aligned} \right\} \quad (9.12)$$

$$\left. \begin{aligned} u_{y1} &= [A \exp(ik\gamma z) + B \exp(-ik\gamma z)] \exp[ik(x - V_L t)] \\ u_{y2} &= C \exp(-ik\gamma' z) \exp[ik(x - V_L t)] \end{aligned} \right\} \quad (9.13)$$

where k , λ , ω and V_L are wave number, wave length, angle frequency and propagation velocity of Love wave, respectively.

$$\text{wave number (波数)} : k = \frac{2\pi}{\lambda} = \frac{\omega}{V_L} \quad (9.14)$$

$$\text{wave length (波長)} : \lambda = \frac{V_L}{f} = \frac{V_L}{2\pi\omega} \quad (9.15)$$

And

$$\left. \begin{aligned} \gamma^2 &= \frac{V_L^2}{V_{s1}^2} - 1 \\ \gamma'^2 &= 1 - \frac{V_L^2}{V_{s2}^2} \end{aligned} \right\} \quad (9.16)$$

Determination of A, B, C based on boundary condition.(B.C.)

$$\text{B.C.} \left\{ \begin{aligned} \sigma_{ij} &= 0 \quad \text{at surface}(z = -H) \quad \text{free surface} \\ \sigma_{ij}^1 &= \sigma_{ij}^2 \quad \text{at int erface}(z = 0) \quad \text{continuity} \\ u_{y1} &= u_{y2} \quad \text{at int erface}(z = 0) \quad \text{continuity} \end{aligned} \right. \quad (9.17)$$

$$\begin{pmatrix} \exp(-ik\gamma H) & -\exp(-ik\gamma H) & 0 \\ 1 & 1 & -1 \\ iG_1\gamma & -iG_1\gamma & G_1\gamma' \end{pmatrix} \begin{pmatrix} A \\ B \\ C \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad (9.18)$$

$$\begin{vmatrix} \exp(-ik\gamma H) & -\exp(-ik\gamma H) & 0 \\ 1 & 1 & -1 \\ iG_1\gamma & -iG_1\gamma & G_2\gamma' \end{vmatrix} = 0 \quad (9.19)$$

$$\tan k\gamma H = \frac{G_2\gamma'}{G_1\gamma} \quad (9.20)$$

Elimination of A and B

$$\left. \begin{aligned} u_{y1} &= C \cos[k\gamma(z + H)] \exp[ik(x - V_L t)] \\ u_{y2} &= \frac{C}{\cos k\gamma H} \exp(-k\gamma' z) \exp[ik(x - V_L t)] \end{aligned} \right\} \quad (9.21)$$

$$u_{y1} = \frac{C}{2} [\exp\{ik(\gamma z + x - V_L t + \gamma H)\} + \exp\{ik(-\gamma z + x - V_L t - \gamma H)\}] \quad (9.22)$$

(downward wave) + (upward wave)

– *Properties of Love Wave*

• *Existence / No-existence of solution*

$$\text{Existence condition: } V_{s1} \leq V_L \leq V_{s2} \quad (9.23)$$

$$\text{Non-existence condition: } V_{s1} > V_{s2} \quad (9.24)$$

• *Dispersion (分散)*

Velocity V_L is dependent of wave length and frequency

body waves are independent of wave length and frequency.

• *No-reflection on the interface*

$$\sin \theta = \frac{1}{\sqrt{1 + \gamma^2}} = \frac{V_{s1}}{V_L} \quad (9.25)$$

$$\sin \theta = \frac{V_{s1}}{V_{s2}} \quad (9.26)$$

$$V_{s2} > V_L \quad (9.27)$$

• *Phase*

$$A = E \quad (9.28)$$

$$B = D \quad (9.29)$$

(b) *Rayleigh Wave*

– *Half infinite elastic body*($z = 0$: *surface*)

$$\left. \begin{aligned} u_x &= u_x(x, z, t) \\ u_y &= u_y(x, y, t) \end{aligned} \right\} u_i \text{ is independent of } y \text{ (assumption)} \quad (9.30)$$

Total Displacement = Dilatation + Rotation(Shear)

$$\left. \begin{aligned} u_x &= u_x^d + u_x^r \\ u_z &= u_z^d + u_z^r \end{aligned} \right\} \quad (9.31)$$

$$\left. \begin{aligned} u_x^d &= A \exp(-\alpha z) \exp[ik(x - V_R t)] \\ u_z^d &= A' \exp(-\alpha z) \exp[ik(x - V_R t)] \end{aligned} \right\} \quad (9.32)$$

$$\left. \begin{aligned} u_x^r &= B \exp(-\beta z) \exp[ik(x - V_R t)] \\ u_z^r &= B' \exp(-\beta z) \exp[ik(x - V_R t)] \end{aligned} \right\} \quad (9.33)$$

For Dilatation(assumption)

$$\omega_x = \omega_y = \omega_z = 0 \quad \rightarrow \quad A' \quad (9.34)$$

$$\varepsilon_v = \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = \frac{iA}{k} (k^2 - \alpha^2) \exp(-\alpha z) \exp[ik(x - V_R t)] \quad (9.35)$$

$$\alpha^2 = k^2 \left(1 - \frac{V_R^2}{V_p^2} \right) \quad (9.36)$$

For Dilatation(assumption)

$$\varepsilon_v = \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = 0 \quad \rightarrow \quad B' \quad (9.37)$$

$$\beta^2 = k^2 \left(1 - \frac{V_R^2}{V_s^2} \right) \quad (9.38)$$

For Total Displacement

$$\left. \begin{aligned} u_x^d &= [A \exp(-\alpha z) + B \exp(-\beta z)] \exp[ik(x - V_R t)] \\ u_z^d &= \left[\frac{i\alpha}{k} A \exp(-\alpha z) + \frac{ik}{\beta} \exp(-\beta z) \right] \exp[ik(x - V_R t)] \end{aligned} \right\} \quad (9.39)$$

From Boundary Condition

$$\left. \begin{aligned} \sigma_{zz} &= 0 \\ \sigma_{zx} &= 0 \end{aligned} \right\} \quad (9.40)$$

$$\left. \begin{aligned} [k^2 - \alpha^2(\lambda + 2\mu)]A - 2k^2\mu B &= 0 \\ 2\alpha\beta A + (\beta^2 + k^2)B &= 0 \end{aligned} \right\} \quad (9.41)$$

$$\begin{bmatrix} [k^2 - \alpha^2(\lambda + 2\mu)] & -2k^2\mu \\ 2\alpha\beta & (\beta^2 + k^2) \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = 0 \quad (9.42)$$

Characteristic Equation for V_R : solutions except for $A = B = 0$

$$\det \begin{bmatrix} [k^2 - \alpha^2(\lambda + 2\mu)] & -2k^2\mu \\ 2\alpha\beta & (\beta^2 + k^2) \end{bmatrix} = 0 \quad (9.43)$$

$$\left(2 - \frac{V_R^2}{V_s^2}\right)^2 = 4 \sqrt{\left(1 - \frac{V_R^2}{V_p^2}\right)} \sqrt{\left(1 - \frac{V_R^2}{V_s^2}\right)} \quad (9.44)$$

$$\therefore V_R < V_s < V_p \quad (9.45)$$

– Properties of Love Wave

- **Velocity**

$$V_R < V_s < V_p$$

$$\text{if } \lambda = \mu (V_p = \sqrt{3}V_s), \quad V_s = 0.9194 V_R$$

- **Considerably reduction of amplitude with an increase with depth z : see Eq.(9.39)**
- **Difference of $\pi/2$ in phase among displacements in the vertical direction z and horizontal propagation direction x : see Eq.(9.39) and Figure with motion of particle.**
- **$\text{Amp}|u_x| \neq \text{Amp}|u_z|$**
- **No Dispersion??**
 - **With existence of surface layer, it shows dispersion behavior**